# **Basic Elements of Complexity Theory**

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May 24, 2018

#### **Outline**

- Basic complexity classes
- Polynomial reductions
- NP-completeness



■ A *polynomial-time algorithm* is one whose worst-case running time T(n), on input size n, is  $O(n^k)$  for some *constant* k

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is A a malumanaial time a algorithma?

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T(10)

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| $T(n) = n^2$          | Yes                               |
| $T(n)=n^3-2n^2-5$     | Yes                               |
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| T(n) = 5                      | Yes                               |
| $T(n) = n^{-7} \cdot 2^{n/7}$ |                                   |

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**Examples:** 

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Add

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|-----------|-------------------------|
| Add       | O(n)                    |

#### **Examples:**

| Algorithm     | worst-case running time |
|---------------|-------------------------|
| ADD           | <i>O</i> ( <i>n</i> )   |
| Thee Manuages |                         |

TREE-MINIMUM

| Algorithm    | worst-case running time |
|--------------|-------------------------|
| Add          | <i>O</i> ( <i>n</i> )   |
| TREE-MINIMUM | <i>O</i> ( <i>n</i> )   |

| Algorithm    | worst-case running time |
|--------------|-------------------------|
| Add          | O(n)                    |
| TREE-MINIMUM | <i>O</i> ( <i>n</i> )   |
| RB-INSERT    |                         |

| worst-case running time |
|-------------------------|
| O(n)                    |
| <i>O</i> ( <i>n</i> )   |
| $O(\log n)$             |
|                         |

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|-------------------|-------------------------|
| Add               | O(n)                    |
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| RB-INSERT         | $O(\log n)$             |
| INORDER-TREE-WALK |                         |

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| RB-INSERT         | $O(\log n)$             |
| INORDER-TREE-WALK | <i>O</i> ( <i>n</i> )   |

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| Add               | <i>O</i> ( <i>n</i> )   |
| TREE-MINIMUM      | <i>O</i> ( <i>n</i> )   |
| RB-INSERT         | $O(\log n)$             |
| INORDER-TREE-WALK | <i>O</i> ( <i>n</i> )   |
| Insertion-Sort    |                         |

| worst-case running time |
|-------------------------|
| <i>O</i> ( <i>n</i> )   |
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| $O(\log n)$             |
| <i>O</i> ( <i>n</i> )   |
| $O(n^2)$                |
|                         |

# **Examples:**

| Algorithm         | worst-case running time |
|-------------------|-------------------------|
| Add               | <i>O</i> ( <i>n</i> )   |
| TREE-MINIMUM      | <i>O</i> ( <i>n</i> )   |
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| INORDER-TREE-WALK | <i>O</i> ( <i>n</i> )   |
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| HEAPSORT          |                         |

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| Boyer-Moore       |                         |

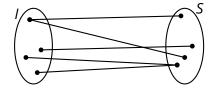
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| •••               |                         |



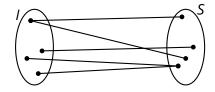
#### **Abstract Problems**

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- A **concrete problem** Q is one where I and S are the set of binary strings  $\{0, 1\}^*$ 
  - ► for all practical purposes, instances and solutions can be **encoded** as binary strings (i.e., mapped into {0, 1}\*)
  - we consider only sensible encodings...



#### **Decision Problems**

■ A *decision problem* Q is one where the set of solutions is  $S = \{0, 1\}$ 

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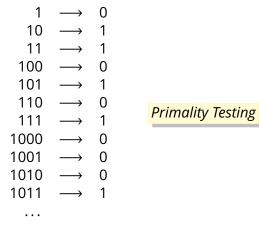
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#### **Example:**





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**Example:** shortest path in a graph

$$G = (V = \{a, b, c, \ldots\}, E = \{(a, c), \ldots\}), a, z \longrightarrow a, c, \ldots, z$$

- ▶ input: a graph G, a start vertex (a), and an end vertex (z)
- output: a sequence of vertexes  $a, c, \ldots, z$

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Shortest path as a decision problem

$$G = (V = \{a, b, c, \ldots\}, E = \{(a, c), \ldots\}), a, z, 10 \longrightarrow 1$$

- ▶ input: a graph G, a start vertex (a), an end vertex (z), and a path length (10)
- output: 1 if there is a path of (at most) the given length



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- An optimization problem is *not much harder* than the corresponding decision problem
  - having a solution to the decision problem does not give an immediate solution to the optimization problem
  - but we can typically use the decision problem as a subroutine in some kind of (binary) search to solve the corresponding optimization problem



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- primality—a relatively recent theoretical result...
  - in 2002: Agrawal, Kayal, and Saxena from IIT Kanpur
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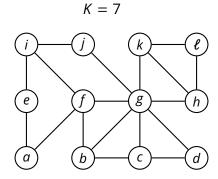
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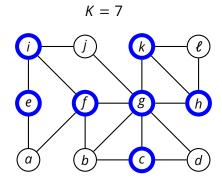
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- parsing a Java program
- **•** ...

- **Example:** *Vertex cover* (decision variant)
  - ▶ *Input*: A graph G = (V, E) and a number K
  - ▶ Output: 1, if there is set S of at most k vertices such that for every edge  $e = (u, v) \in E$ ,  $u \in S$  or  $v \in S$  (or both); 0 otherwise

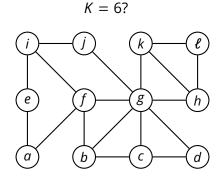
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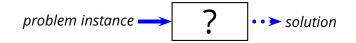
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*problem instance* → ? ··· > solution

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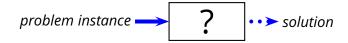


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- Examples
  - longest path (decision variant)
  - knapsack (decision variant)



■ A concrete decision problem Q is **polynomial-time verifiable** if there is a polynomial-time algorithm A and a constant c such that, for each instance  $x \in I$ , there is a **certificate** y of polynomial-size  $|y| = O(|x|^c)$  such that A(x, y) = 1

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■ NP does not mean non-polynomial!

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 $P \subseteq NP$ 



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$$P = NP?$$

- Most theoretical computing scientists *believe* that  $P \neq NP$
- Finding a solution to a problem is believed to be inherently more difficult than verifying a given solution or a proof of a solution



- Satisfiability problem (SAT)
  - ► *Input*: a Boolean formula of n (Boolean) variables  $x_1, x_2, \ldots, x_n$
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- Examples

  - $\blacktriangleright (x \lor y \lor z) \land (x \lor \neg y) \land (y \lor \neg z) \land (z \lor \neg x) \land (\neg x \lor \neg y \lor \neg z)$

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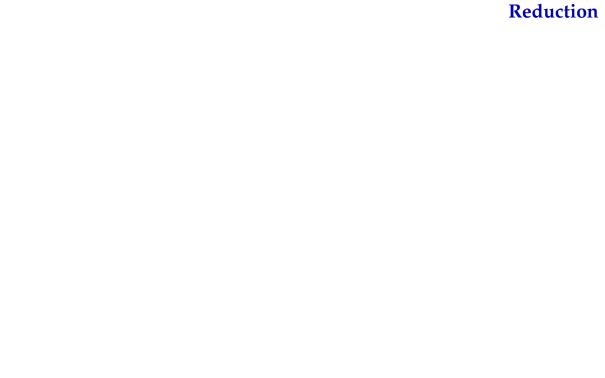
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- SAT  $\in$  NP?
  - yes: given an assignment that satisfies the formula, it is easy (poly-time) to verify that the formula is satisfiable
- SAT  $\in$  P?
  - we don't know



■ In our theory of complexity we want to show that a problem is *just as hard as another problem* 

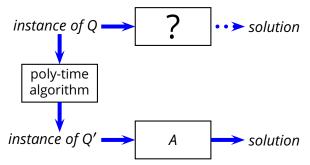
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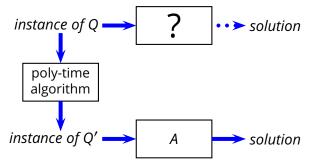
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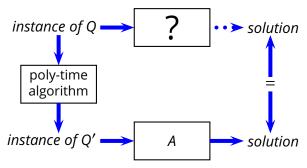


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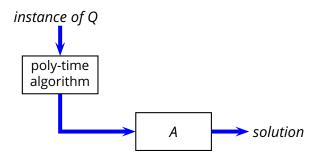
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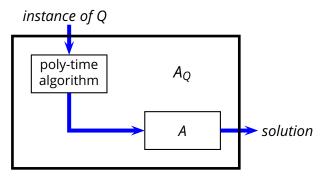
- ► an instance *q* of *Q* is transformed into an instance *q'* of *Q'* through a polynomial-time algorithm
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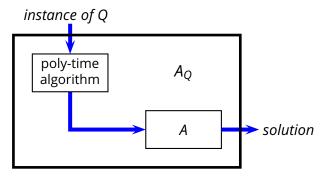
■ Solution by polynomial-time reductions to a solvable problem



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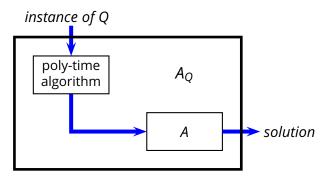


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■ Solution by polynomial-time reductions to a solvable problem



- if A is polynomial-time, then of  $A_0$  is also polynomial time
- ▶ therefore if  $Q' \in P$ , then  $Q \in P$



### **Example: 2-CNF-SAT**

#### ■ 2-CNF-SAT problem

#### Input:

- ► f is a Boolean formula of n (Boolean) variables  $x_1, x_2, \ldots, x_n$
- f is in conjunctive normal form (CNF), so  $f = C_1 \wedge C_2 \wedge \cdots \wedge C_k$
- every *clause*  $C_i$  of f contains exactly *two* literals (a variable or its negation)

#### **Output:** 1 iff *f* is satisfiable

ightharpoonup there is an assignment of variables that satisfies f

#### **Example:**

$$(x_1 \vee \neg x_3) \wedge (\neg x_2 \vee x_3) \wedge (\neg x_1 \vee \neg x_3) \wedge (x_1 \vee x_2)$$



## 2-CNF-SAT to Implicative Form

Consider each clause *C<sub>i</sub>* 

$$(a \lor b) \equiv (\neg a \Rightarrow b) \equiv (\neg b \Rightarrow a)$$

so we can rewrite a 2-CNF-SAT formula f into another formula in *implicative* normal form

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**Example:** 

$$(x_1 \vee \neg x_3) \wedge (\neg x_2 \vee x_3)$$

is equivalent to

$$(\neg x_1 \Rightarrow \neg x_3) \land (x_3 \Rightarrow x_1) \land (x_2 \Rightarrow x_3) \land (\neg x_3 \Rightarrow \neg x_2)$$

# 2-CNF-SAT to Graph Reachability

$$(x_1 \vee \neg x_3) \wedge (\neg x_2 \vee x_3) \wedge (\neg x_1 \vee \neg x_3) \wedge (x_1 \vee x_2)$$

# 2-CNF-SAT to Graph Reachability

$$(x_1 \lor \neg x_3) \land (\neg x_2 \lor x_3) \land (\neg x_1 \lor \neg x_3) \land (x_1 \lor x_2)$$

$$\downarrow \uparrow \uparrow$$

$$(\neg x_1 \Rightarrow \neg x_3) \land (x_3 \Rightarrow x_1) \land (x_2 \Rightarrow x_3) \land (\neg x_3 \Rightarrow \neg x_2) \land$$

$$(x_1 \Rightarrow \neg x_3) \land (x_3 \Rightarrow \neg x_1) \land (\neg x_1 \Rightarrow x_2) \land (\neg x_2 \Rightarrow x_1)$$

$$(x_{1} \vee \neg x_{3}) \wedge (\neg x_{2} \vee x_{3}) \wedge (\neg x_{1} \vee \neg x_{3}) \wedge (x_{1} \vee x_{2})$$

$$\downarrow \uparrow \uparrow$$

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$$x_{2}$$

$$x_{1}$$

$$x_{3}$$

$$x_{3}$$

$$(x_{1} \lor \neg x_{3}) \land (\neg x_{2} \lor x_{3}) \land (\neg x_{1} \lor \neg x_{3}) \land (x_{1} \lor x_{2})$$

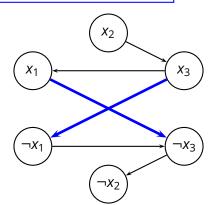
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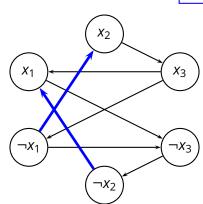
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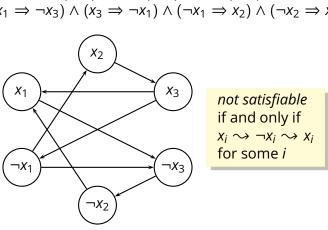


$$(x_1 \lor \neg x_3) \land (\neg x_2 \lor x_3) \land (\neg x_1 \lor \neg x_3) \land (x_1 \lor x_2)$$

$$\Downarrow \uparrow \uparrow$$

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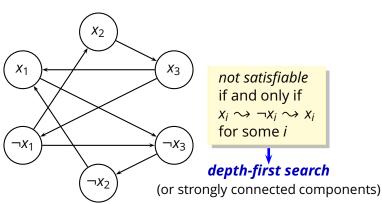


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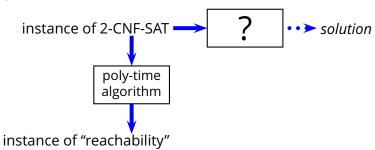




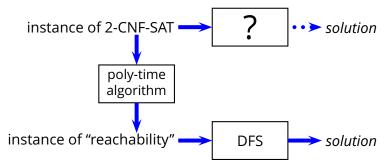
■ 2-CNF-SAT ∈ *P* 

instance of 2-CNF-SAT — ? solution

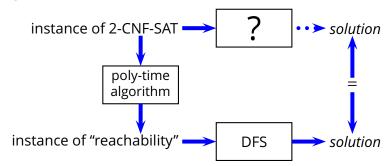
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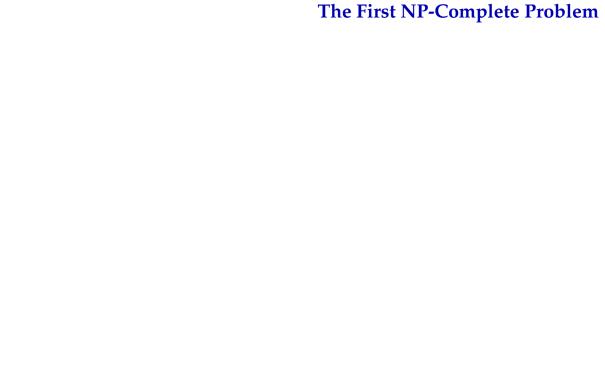
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- If Q' is NP-hard and polynomial-time solvable, then P = NP
  - ▶ i.e., most researchers believe that there is no such Q'



## The First NP-Complete Problem

■ Is there any NP-complete problem?

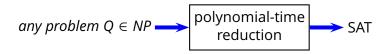
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- Circuit satisfiability (SAT) was the first problem that was proved NP-hard and, since SAT ∈ NP, also NP-complete
- Many other problems were then proved NP-complete through polynomial reductions
  - e.g., SAT is polynomial-time reducible to the *longest path* problem
  - therefore, the *longest path* problem is also NP-complete