

Basic Elements of Complexity Theory

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- Basic complexity classes
- Polynomial reductions
- NP-completeness

Polynomial Time

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Polynomial-Time Algorithms

- **Examples:**

Algorithm

worst-case running time

Polynomial-Time Algorithms

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<u>Algorithm</u>	<u>worst-case running time</u>
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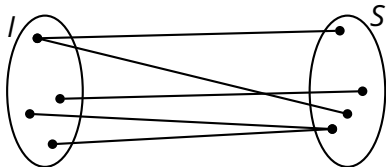
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Abstract Problems

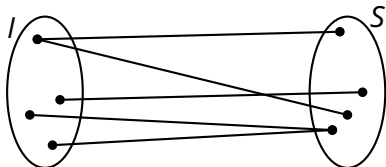
Abstract Problems

- An **abstract problem** Q is a binary relation between a set I of problem **instances** and a set S of **solutions**



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- A **concrete problem** Q is one where I and S are the set of binary strings $\{0, 1\}^*$
 - ▶ for all practical purposes, instances and solutions can be **encoded** as binary strings (i.e., mapped into $\{0, 1\}^*$)
 - ▶ we consider only sensible encodings...

Decision Problems

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Primality Testing

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Example: shortest path in a graph

$$G = (V = \{a, b, c, \dots\}, E = \{(a, c), \dots\}), a, z \longrightarrow a, c, \dots, z$$

- ▶ *input:* a graph G , a start vertex (a), and an end vertex (z)
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Shortest path as a decision problem

$$G = (V = \{a, b, c, \dots\}, E = \{(a, c), \dots\}), a, z, 10 \longrightarrow 1$$

- ▶ *input:* a graph G , a start vertex (a), an end vertex (z), and a path length (10)
- ▶ *output:* 1 if there is a path of (at most) the given length

Decision Problems (3)

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- An optimization problem is *not much harder* than the corresponding decision problem
 - ▶ having a solution to the decision problem does not give an immediate solution to the optimization problem
 - ▶ but we can typically use the decision problem as a subroutine in some kind of (binary) search to solve the corresponding optimization problem

The Complexity Class P

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- A concrete decision problem Q is ***polynomial-time solvable*** if there is a polynomial-time algorithm A that solves it

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 - ▶ in 2002: Agrawal, Kayal, and Saxena from IIT Kanpur
 - ▶ *Neeraj Kayal and Nitin Saxena were Bachelor students!*

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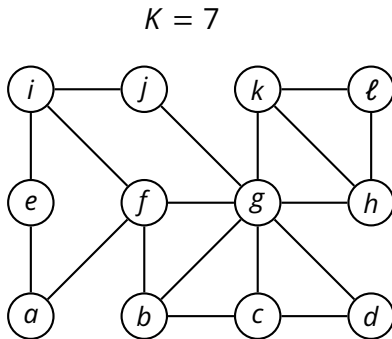
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 - ▶ parsing a Java program
 - ▶ ...

■ Example: *Vertex cover*

- ▶ *Input*: A graph $G = (V, E)$ and a number K
- ▶ *Output*: A set of k vertices S such that for every edge $e = (u, v) \in E$, $u \in S$ or $v \in S$

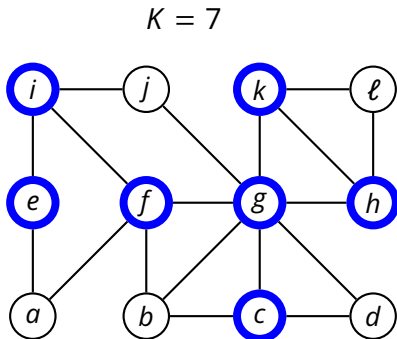
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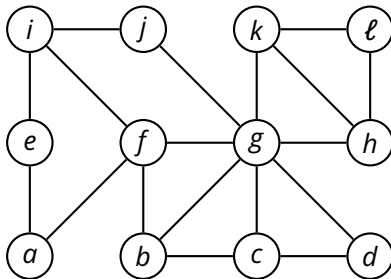
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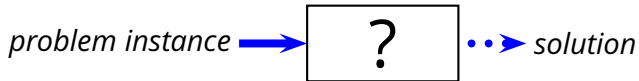
$K = 6?$



Polynomial-Time Verification

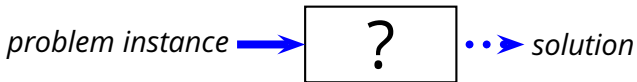
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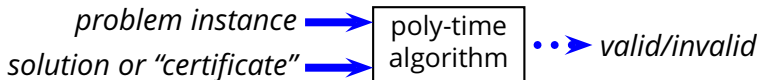


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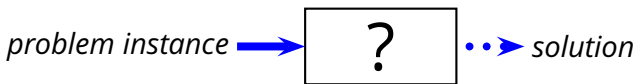


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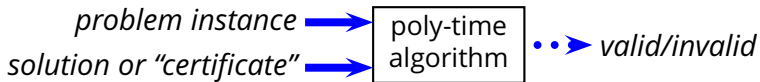


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- Examples
 - ▶ longest path (decision variant)
 - ▶ knapsack (decision variant)

The Complexity Class NP

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- A concrete decision problem Q is **polynomial-time verifiable** if there is a polynomial-time algorithm A and a constant c such that, for each instance $x \in I$, there is a **certificate** y of polynomial-size $|y| = O(|x|^c)$ such that $A(x, y) = 1$

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- **NP does not mean non-polynomial!**
 - ▶ it means “non-deterministic polynomial”
- *polynomial-time solvable* \implies *polynomial-time verifiable*

$$P \subseteq NP$$

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- Or are there problems for which there is a polynomial-time verification algorithm but there are no polynomial-time algorithms to find solutions?

P = NP?

- Most theoretical computing scientists *believe* that $P \neq NP$
- ***Finding a solution to a problem is believed to be inherently more difficult than verifying a given solution or a proof of a solution***

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- ▶ *Input*: a Boolean formula of n (Boolean) variables x_1, x_2, \dots, x_n
- ▶ *Output*: 1 iff there is an assignment of variables that satisfies the formula

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■ Examples

- ▶ $\neg x \wedge (\neg y \vee \neg z) \wedge \neg z \wedge (x \vee y)$

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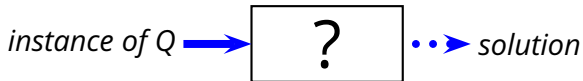
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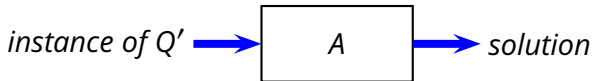
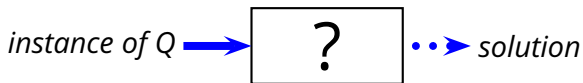
- ▶ we don't know

- In our theory of complexity we want to show that a problem is *just as hard as another problem*

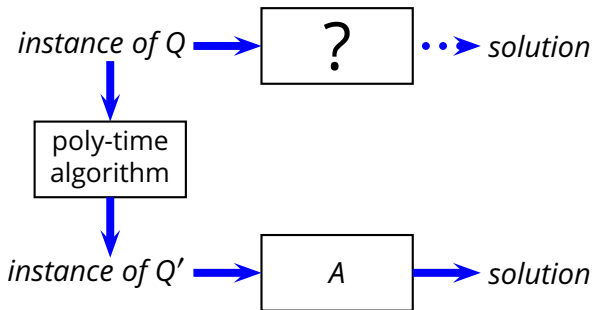
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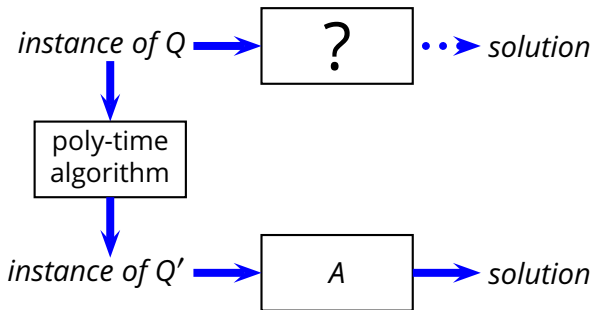
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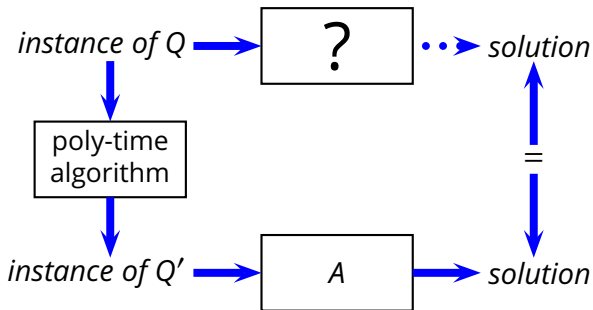


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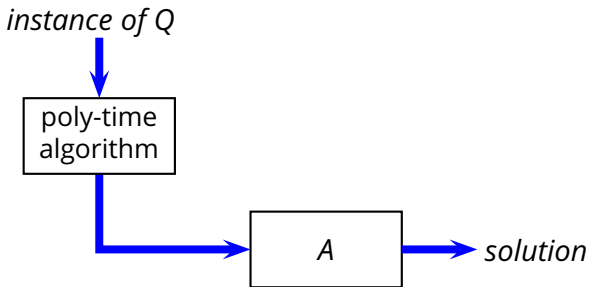
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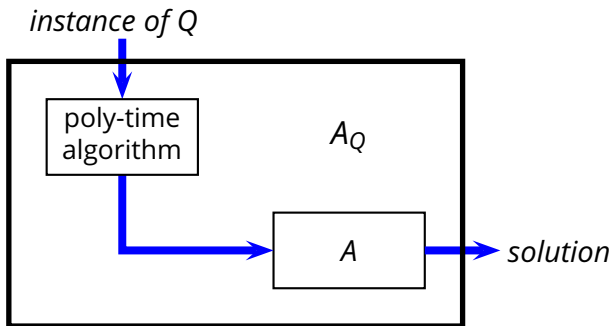
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- Solution by polynomial-time reductions to a solvable problem



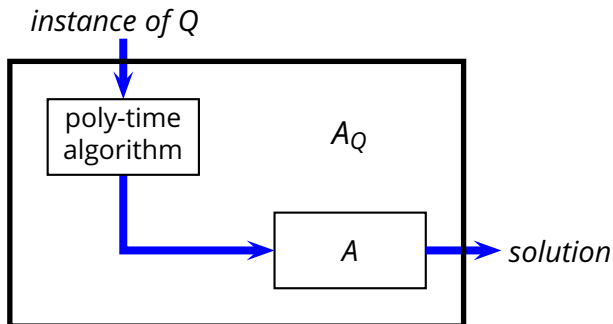
Reduction (2)

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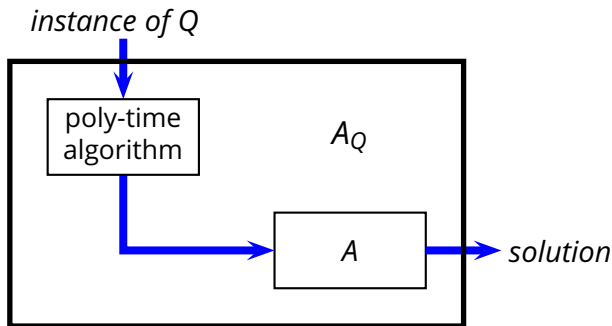
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- Solution by polynomial-time reductions to a solvable problem



- ▶ if A is polynomial-time, then A_Q is also polynomial time
- ▶ therefore if $Q' \in P$, then $Q \in P$

Example: 2-CNF-SAT

■ 2-CNF-SAT problem

Input:

- ▶ f is a Boolean formula of n (Boolean) variables x_1, x_2, \dots, x_n
- ▶ f is in *conjunctive normal form (CNF)*, so $f = C_1 \wedge C_2 \wedge \dots \wedge C_k$
- ▶ every *clause* C_i of f contains exactly *two* literals (a variable or its negation)

Output: 1 iff f is satisfiable

- ▶ there is an assignment of variables that satisfies f

Example:

$$(x_1 \vee \neg x_3) \wedge (\neg x_2 \vee x_3) \wedge (\neg x_1 \vee \neg x_3) \wedge (x_1 \vee x_2)$$

2-CNF-SAT to Implicative Form

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- Consider each clause C_i

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$$(x_1 \vee \neg x_3) \wedge (\neg x_2 \vee x_3)$$

is equivalent to

$$(\neg x_1 \Rightarrow \neg x_3) \wedge (x_3 \Rightarrow x_1) \wedge (x_2 \Rightarrow x_3) \wedge (\neg x_3 \Rightarrow \neg x_2)$$

2-CNF-SAT to Graph Reachability

$$(x_1 \vee \neg x_3) \wedge (\neg x_2 \vee x_3) \wedge (\neg x_1 \vee \neg x_3) \wedge (x_1 \vee x_2)$$

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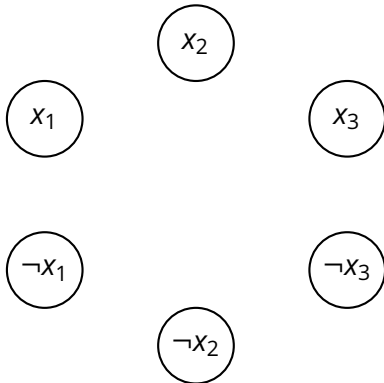
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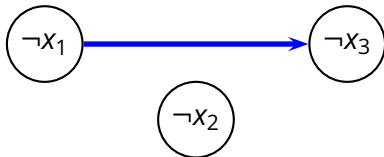
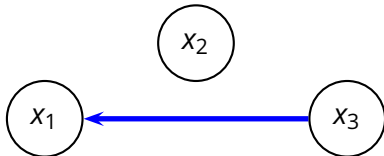


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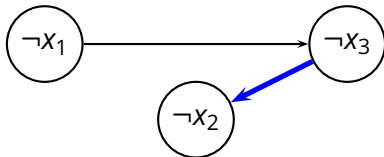
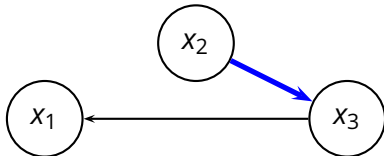
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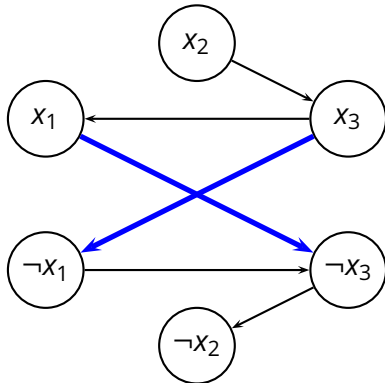


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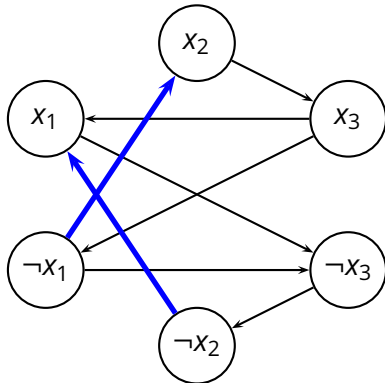


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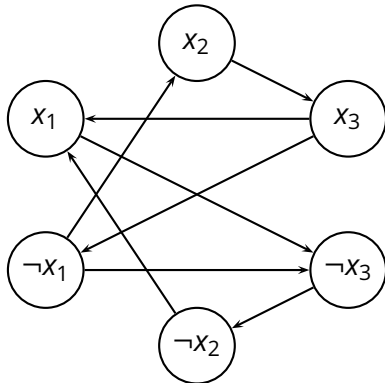


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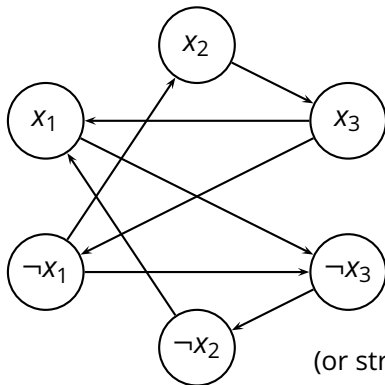
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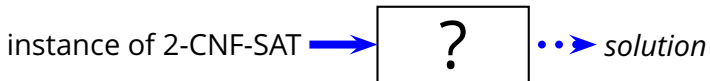
depth-first search

(or strongly connected components)

Reduction of 2-CNF-SAT

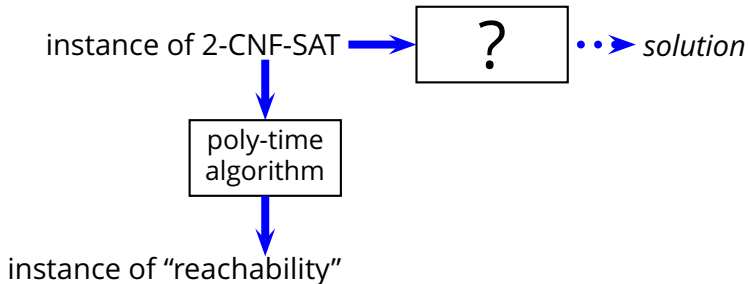
Reduction of 2-CNF-SAT

- 2-CNF-SAT $\in P$



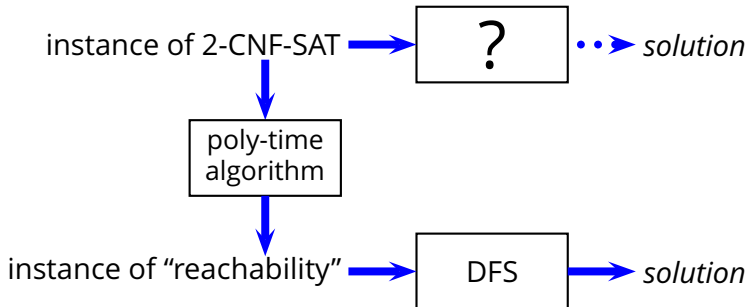
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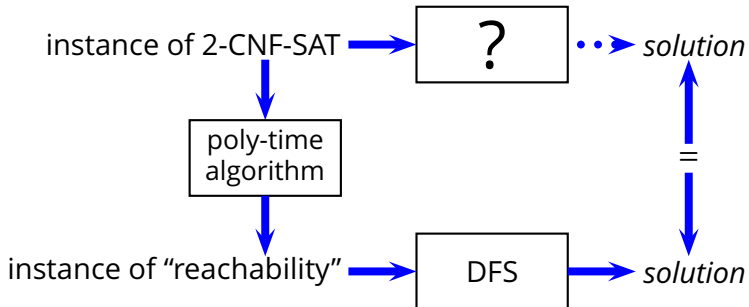
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NP-Completeness

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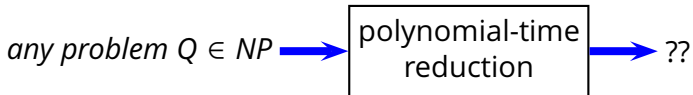
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- If Q' is NP-hard and *polynomial-time reducible to* Q'' , then Q'' is NP-hard
- If Q' is NP-hard and *polynomial-time solvable*, then $P = NP$
 - ▶ i.e., most researchers believe that there is no such Q'

The First NP-Complete Problem

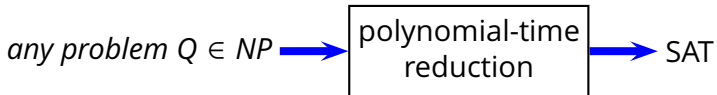
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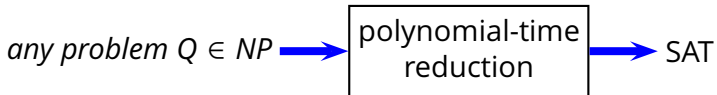
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The First NP-Complete Problem

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- *Circuit satisfiability (SAT)* was the first problem that was proved NP-hard and, since $SAT \in NP$, also NP-complete
- Many other problems were then proved NP-complete through polynomial reductions
 - ▶ e.g., SAT is polynomial-time reducible to the *longest path* problem
 - ▶ therefore, the *longest path* problem is also NP-complete